



GPS Transponder for Space Traffic Management

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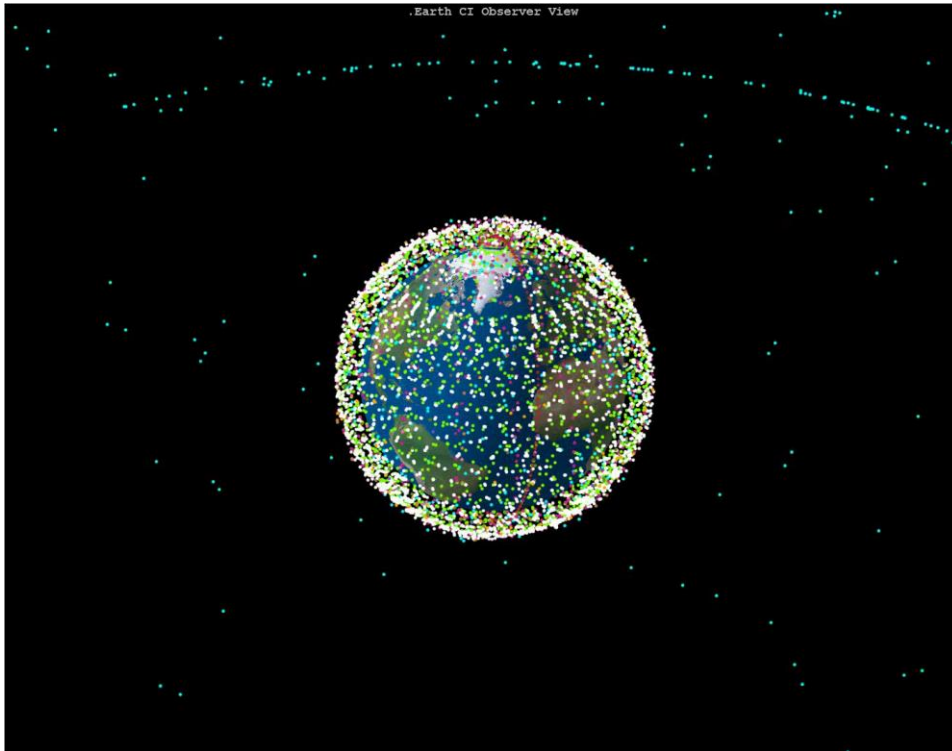


Large Constellations are Proposed

As many as 20,000 new satellites in the next decade

Some possible new constellations

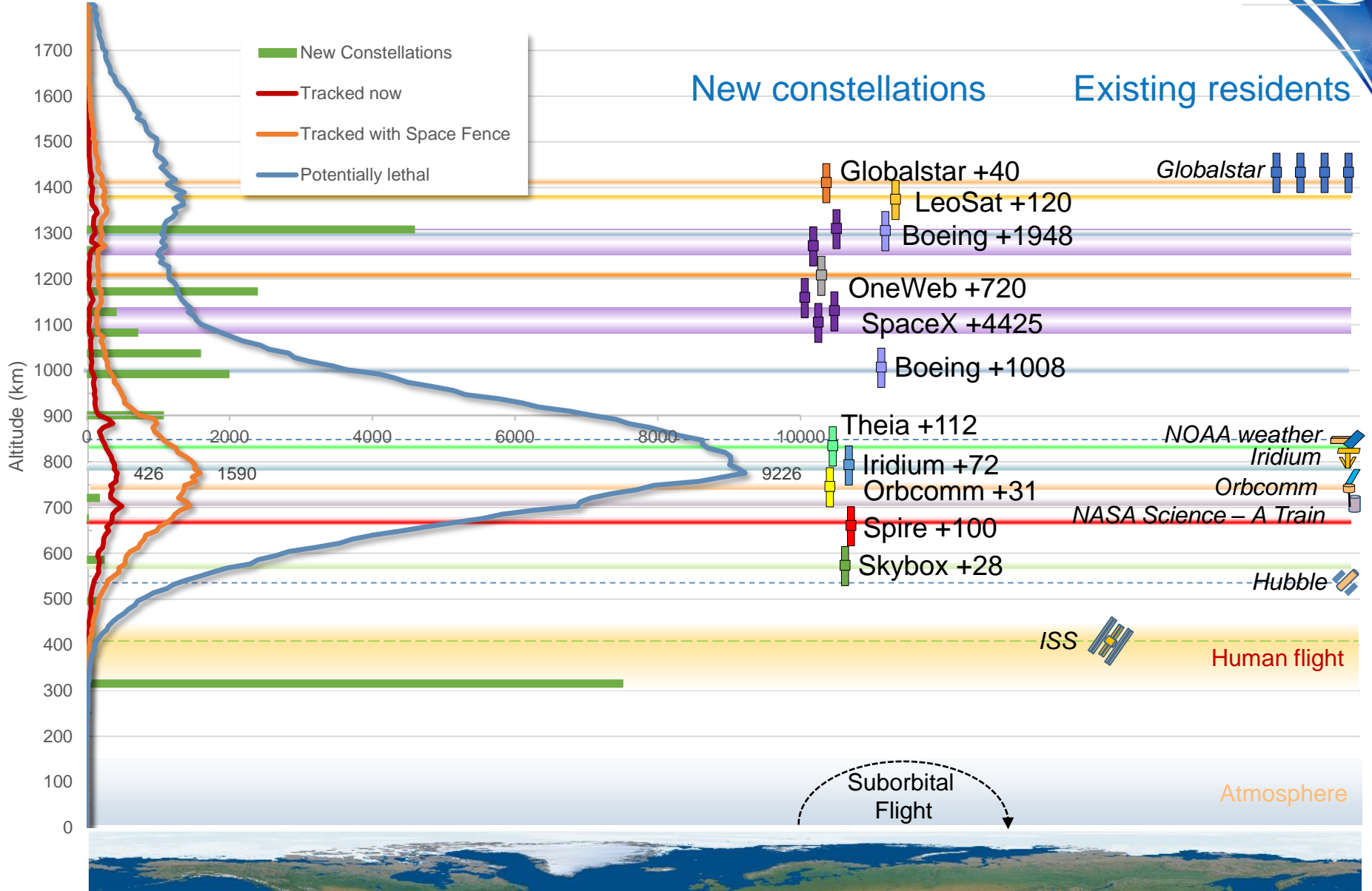
Operator	Num sats	Alt (km)	Incl (deg)
SpaceX V-band	7518	335-345	42-53
Black Sky	60	450	55
Kepler	140	550	97.6
Skybox	28	576	97.8
Yalini	135	600	97.6
Planet	150	675	97.4
Spire	100	651	97.9
Orbcomm	31	750	45
Iridium	72	780	86.4
Theia (3000 kg)	112	800	98.6
Telesat (Canada)	72	1000	99.5
Boeing (1500 kg)	1008	1025	88
SpaceX (400 kg)	4425	1110-1325	53-81
OneWeb (150 kg)	720	1200	88
Telesat (Canada)	45	1248	37.4
Boeing (1500 kg)	1948	1275	45-55
Samsung	4600	1400	99
LeoSat (700 kg)	120	1400	89
Globalstar	40	1410	52



We will see a fundamental change in the LEO environment – Business as Usual will not work anymore



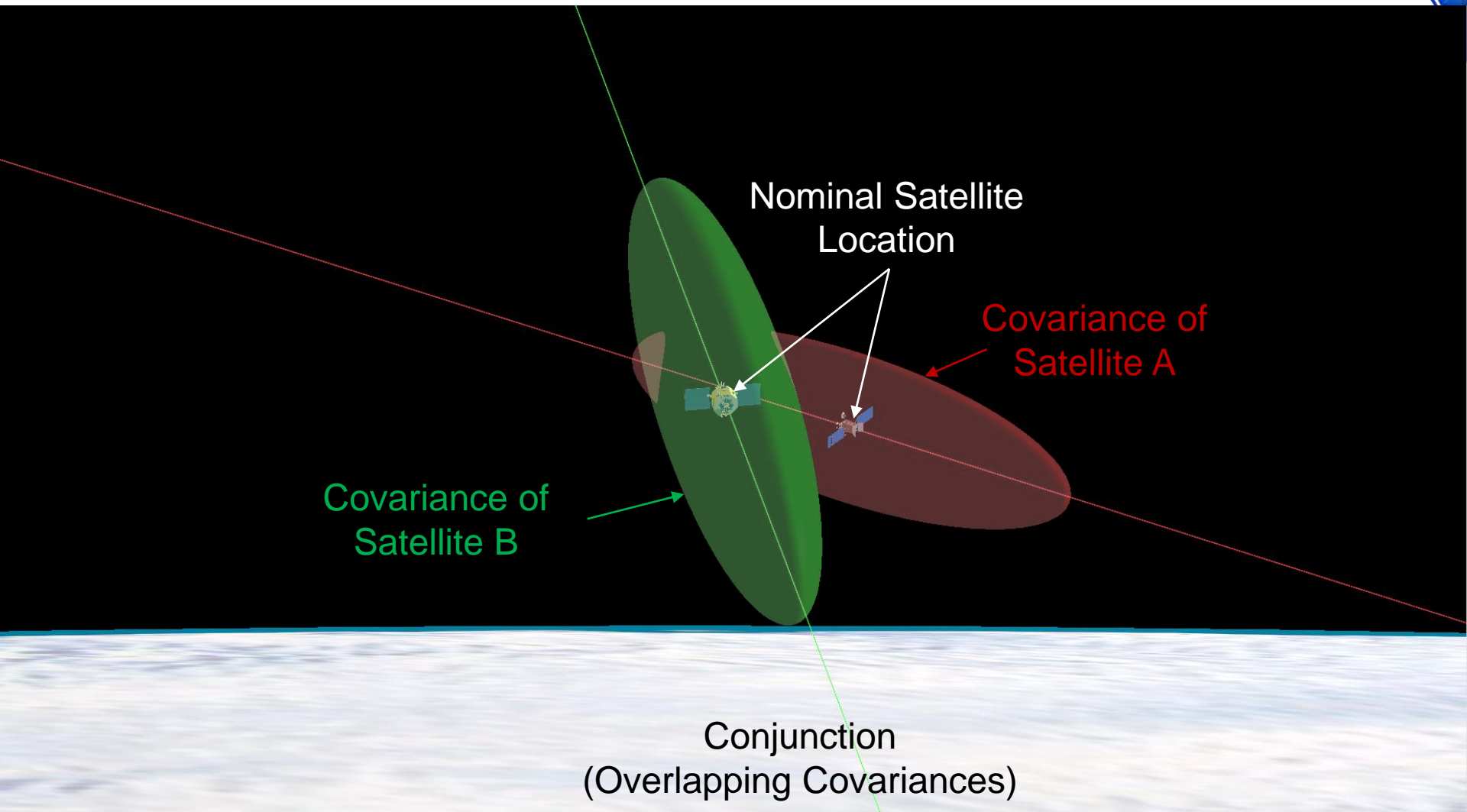
A Combined Threat to Current Missions





Covariance, Conjunction, and Collision Probability

The Positional Uncertainty of a Space Object

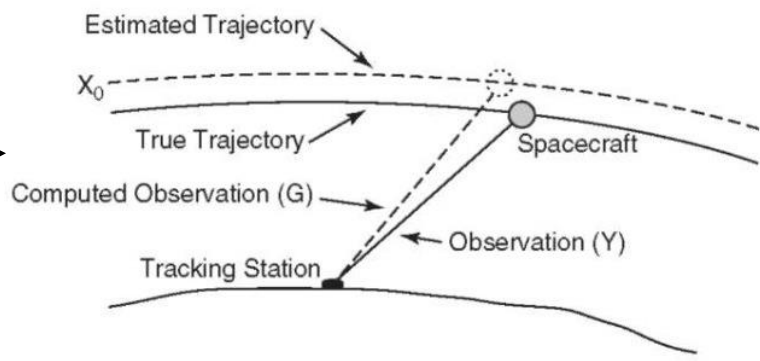
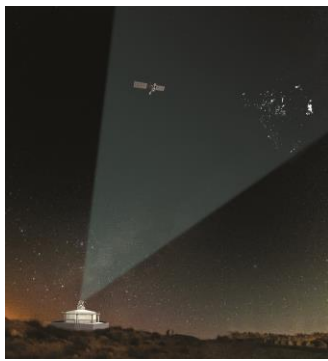


Note: Covariance represents the probability distribution of the object's position (& sometimes velocity).
Note: Integrating the overlapping areas of the two covariance's together allows for the calculation of the probability of collision, P_c .



Overview of Current Space Situational Awareness

Non-Cooperative Tracking Network's Current Collision Avoidance Process



International Designator	SCC Number	Common Name
1957-001A	1	SL-1 R/B
1957-001B	2	SPUTNIK 1
1957-002A	3	SPUTNIK 2
1958-001A	4	EXPLORER 1
1958-002B	5	VANGUARD 1
1958-003A	6	EXPLORER 3

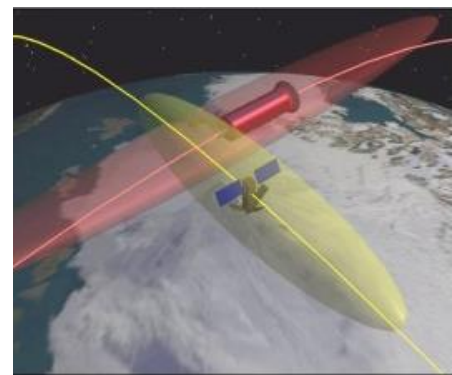
Object Observations

Orbit Determination

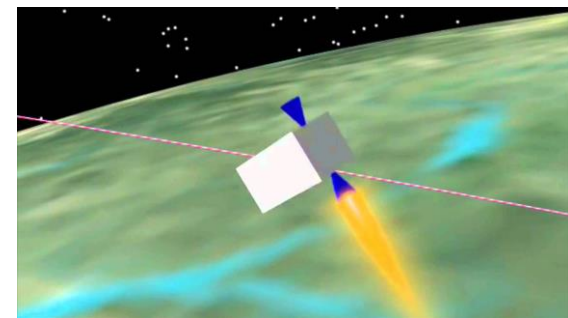
Satellite Catalog Construction



Conjunction Screening



Conjunction WARNING!



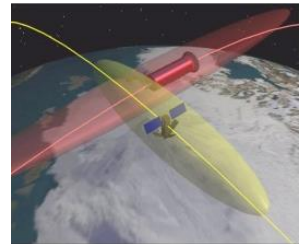
Spacecraft COLA Maneuver



The Problem

Space is Becoming Congested and Contested

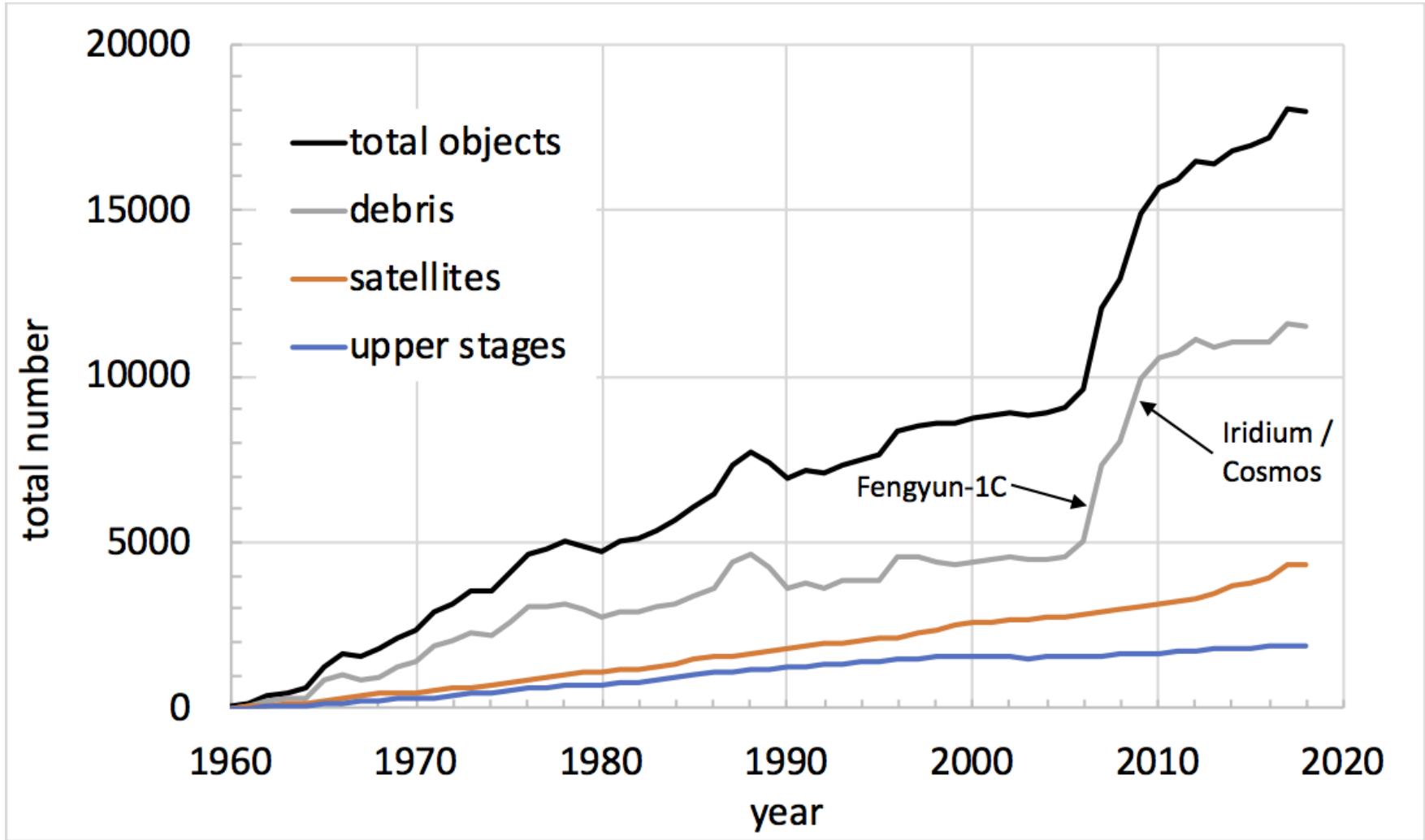
- Space is becoming more congested
 - *Launch prices are decreasing; reusability is a game changing technology*
 - *Large constellations of several thousand satellites are planned by multiple companies*
 - *CubeSats are increasingly popular; more are launched each year*
 - *Space Fence is about to be activated (ballooning the catalog by detecting smaller objects)*
- Operators will see a multiple-order-of-magnitude increase in the frequency of conjunction warning messages*
 - *Today they occur once every month; with future traffic they will occur once per day*
 - *It is costly to respond to conjunction warnings*
 - Responding to one conjunction can consume hundreds of man-hours
 - Maneuvering to avoid a collision uses fuel and significantly shortens mission life
 - Maneuvering takes the spacecraft out-of-mission for several hours (mission specific)
- Number of collisions per year also increases
 - *Goes from 1-2 collisions per decade to 1-2 collisions per year*
- What can be done?
 - *Either limit the number of space objects launched per year or*
 - *Find a way to safely operate more satellites in the same, highly congested environment*





The Problem

SATCAT Growth Over Time

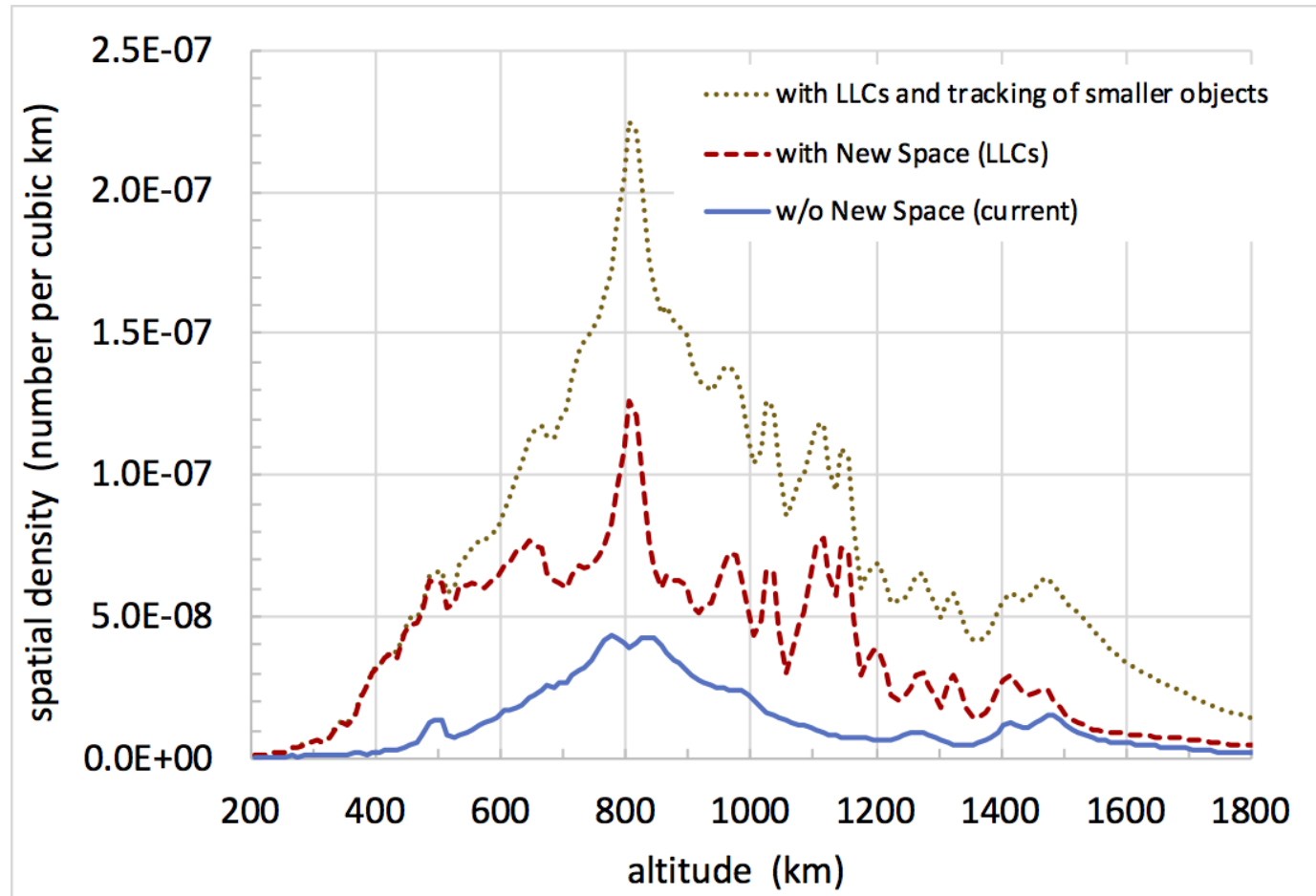


Number of objects in SSN catalog. The number of these objects has increased significantly during the past decade.



The Problem

Space Congestion is Increasing and is Better Known

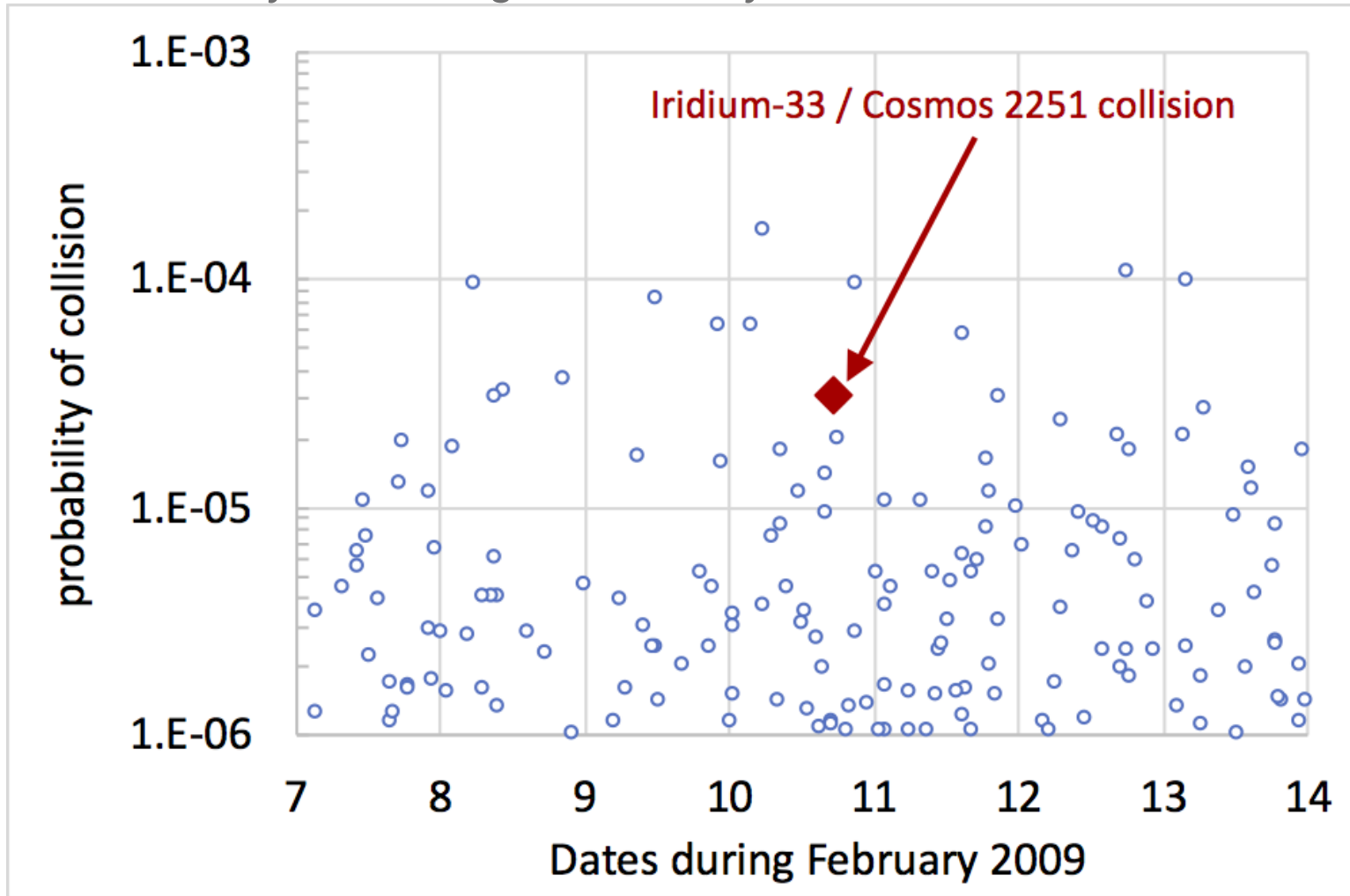


Spatial density of objects in LEO with and without New Space activity. Adding New Space Large LEO Constellations (LLCs) will increase the density at all altitudes due to replenishment, disposal, and failed satellites. Adding the smaller objects that would appear with an improved tracking system could increase the density at all altitudes even more.



The Problem

Collision Probability Screenings Often “Cry Wolf!”

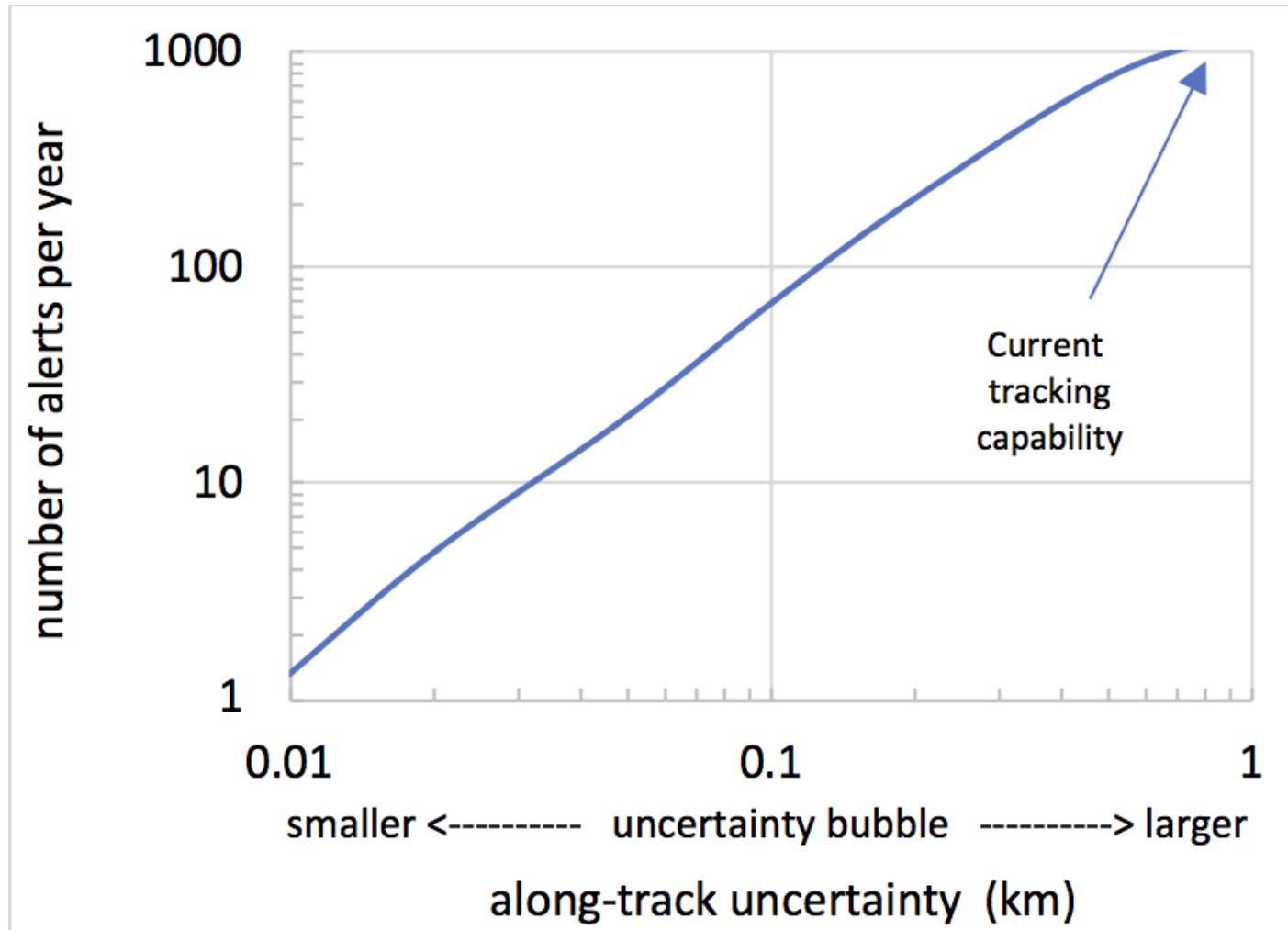


Iridium constellation conjunction probabilities during week of Feb 7, 2009. Under current tracking accuracies, the actual collision between Iridium-33 and Cosmos 2251 did not stand out from other conjunctions that week as being noticeably dangerous.



The Problem

The Solution is to Reduce Your Covariance!

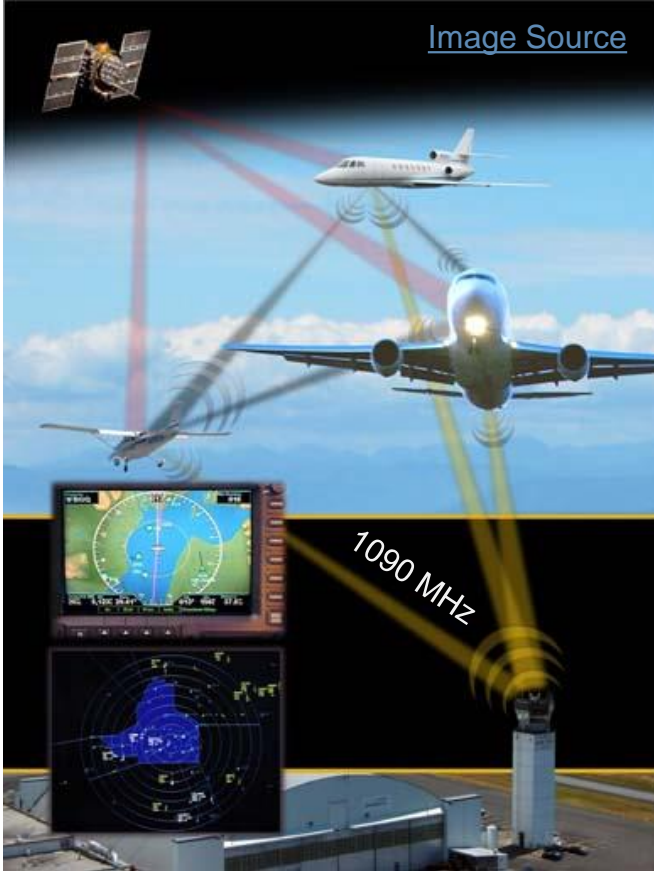


Annual number of expected alerts for Iridium constellation using a threshold probability of 1 in 100,000 (using a present-day catalog)

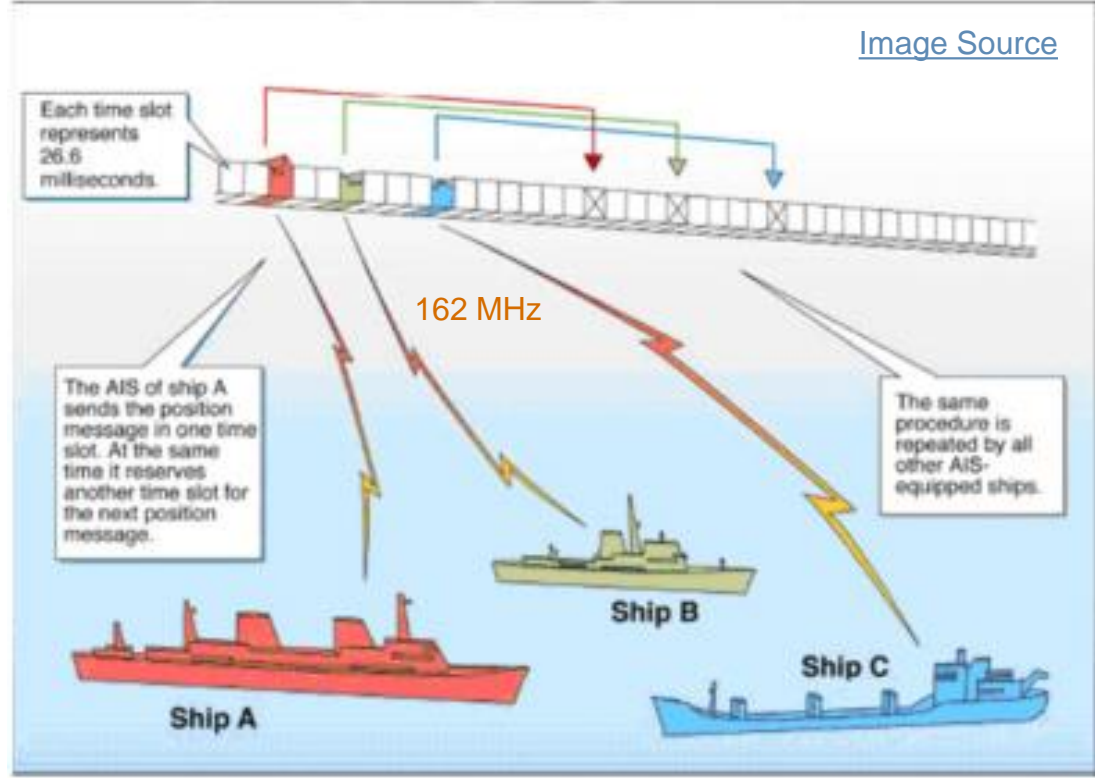


Inspiration from Other Domains

ADS-B (Air Traffic) and AIS (Marine Traffic)



Automatic Dependent Surveillance-Broadcast (ADS-B)



Automatic Identification System (AIS)



The Solution

Value and Objectives of a STM Transponder

An ideal Space Traffic Management transponder will address three primary issues:

- 1) **Exquisite Covariance:** minimize the uncertainty in the position of a space object in order to enhance flight safety for all space operators (i.e. avoiding collisions).*
- 2) **Satellite ID:** how can one quickly, easily, and without ambiguity distinguish one space object from another? (Trust & confidence building measure.)*
- 3) **Tracking while Thrusting:** Non-cooperative tracking networks operate via a track-and-predict methodology. This breaks down for thrusting objects (especially low-thrust).*

*The goal is to design an inexpensive, small, and self-sufficient hosted payload package that will report data at regular intervals to enhance space situational awareness and better enable space traffic management activities. **This should be accomplished even if the host spacecraft is dead, inactive, or otherwise uncontrolled.** It will be used on all intentionally deployed space objects that are able to accommodate a transponder.*



Many Potential Solutions (All Very Experimental)

Significant Trades Between Valuable Data and Size, Weight & Power

Name	Inventor	Mass	Size (cm)	Sponsor	Sat ID	Improved Covariance	Custody During Thrust	<i>a priori</i> Orbit Required	Description
GPS Transponder	The Aerospace Corporation	100 - 150 g	9x6x1.5		Yes	Yes	Yes	No	Using GPS receivers, a radio, solar cells, and a battery
CUBEIT	SRI	100 g		DARPA	Yes	Not Currently	Not Currently	Yes	RFID using Allen Telescope Array
ELROI	Los Alamos National Lab		2x2x0.5		Yes	Not Currently	Not Currently	Yes	LED transmits data to ground telescope (at night) No RFI risk
Spacecraft ID Device	Stellar Exploration			DARPA	Yes	Not Currently	Not Currently		
M2M Self Reporting*	Owner/Operator				Yes	Unknown	Likely		

- All methods have pros and cons (usually \$SWaP vs. capability/reliability)
- No clear “winner” or dominant approach
- All methods have significant value and should be further developed

Disclaimer: Data in this table may be incomplete or outdated; references at end of document



Orbit Determination Comparison of Data Products

Accuracy of Competing Data Products

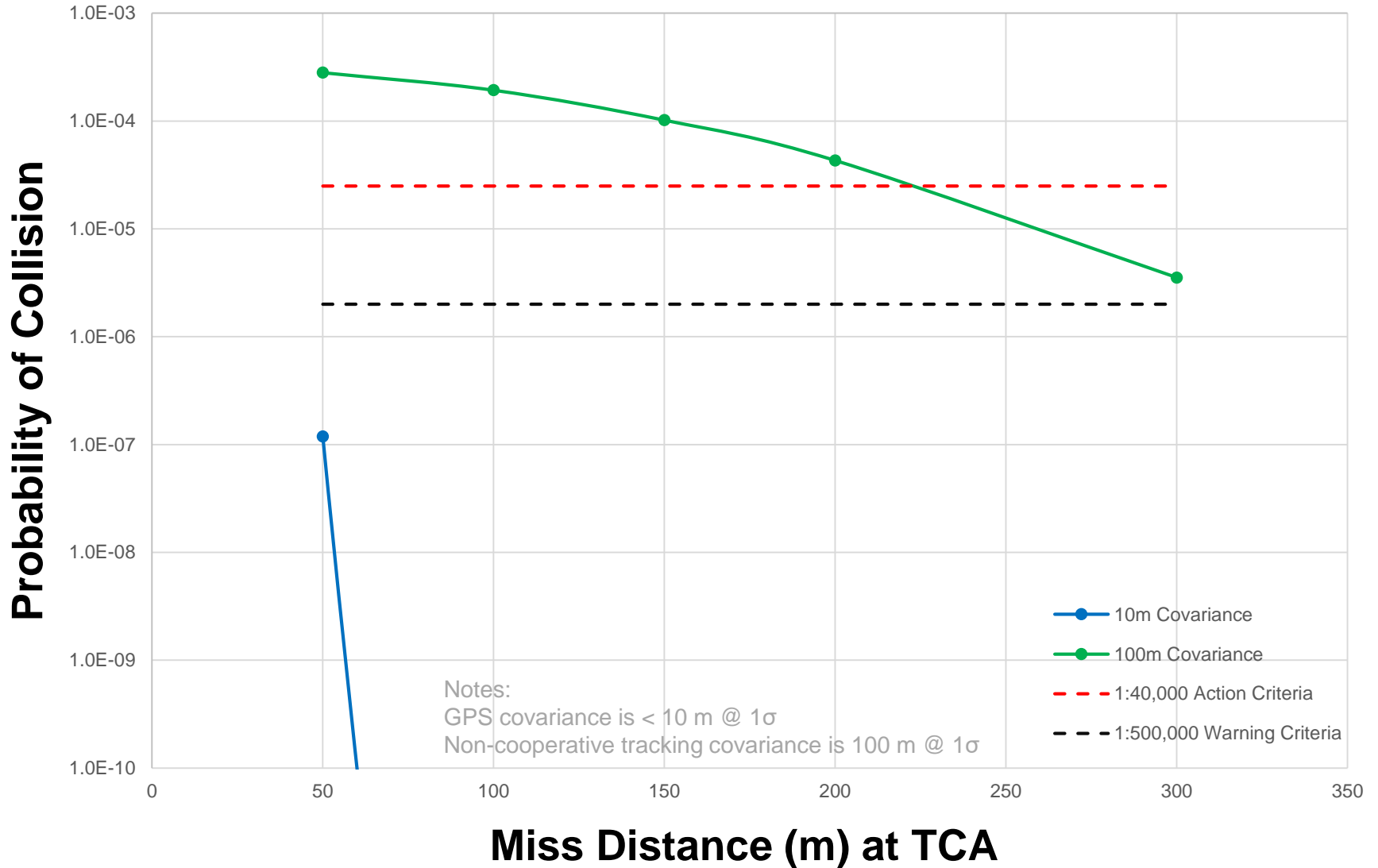
Data Source	Covariance Accuracy
Space-Track.org	Kilometers?
Non-Cooperative Tracking Network	Hundred(s) of meters
M2M Self-Reporting*	10 m using GPS
GPS Transponder	10 m

*Machine-to-Machine Self Reporting: System must be independently verified and validated and have a mature “debris mode” fail-safe to qualify; a.k.a. “virtual transponder”



How Covariance Influences Collision Probability

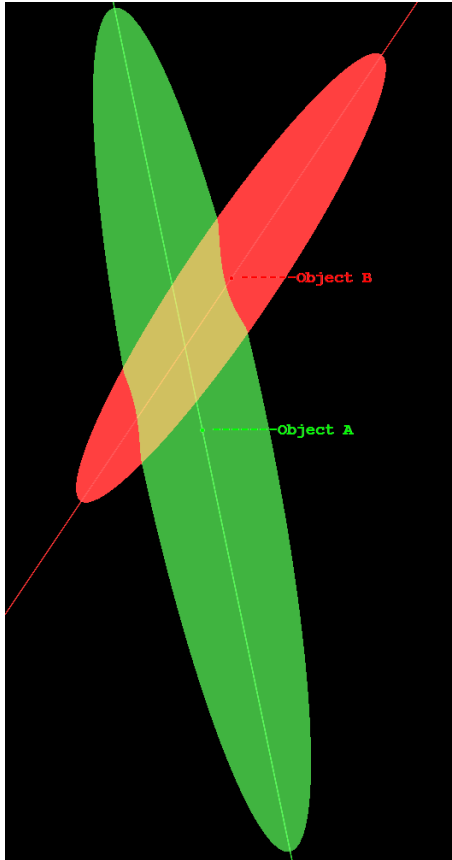
Covariance Size and Miss Distance vs. Collision Probability





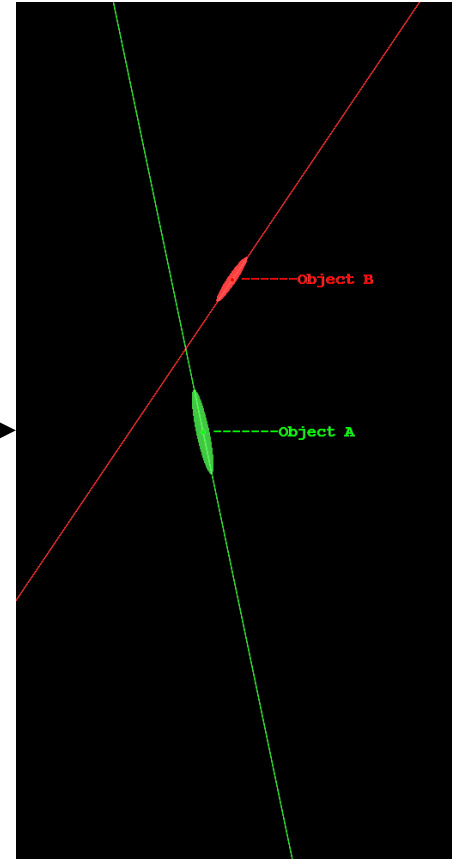
Visualization of Covariance Reduction

The two scenarios are identical except for the covariance size



**Non-Cooperative
Tracking Network
Covariance**

(Shown at Time of Closest Approach)



**GPS Transponder
Covariance**

(Shown at Time of Closest Approach)



Example of Satellite Identification Value

ISRO Deployment of 104 CubeSats on 15 February 2017



Initial Deployment...



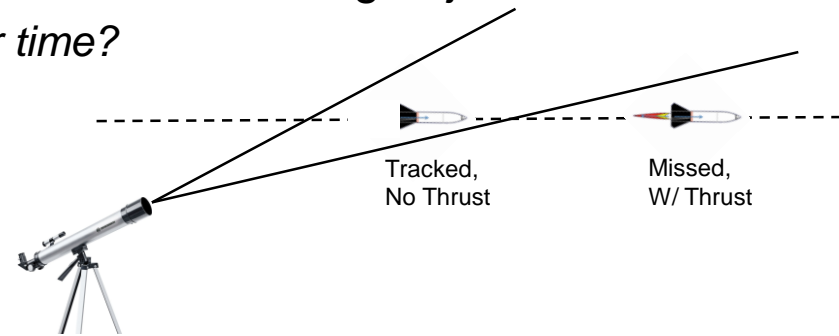
... 150 Seconds Later



Overcoming Track-and-Predict Limitations

Thrusting Issues

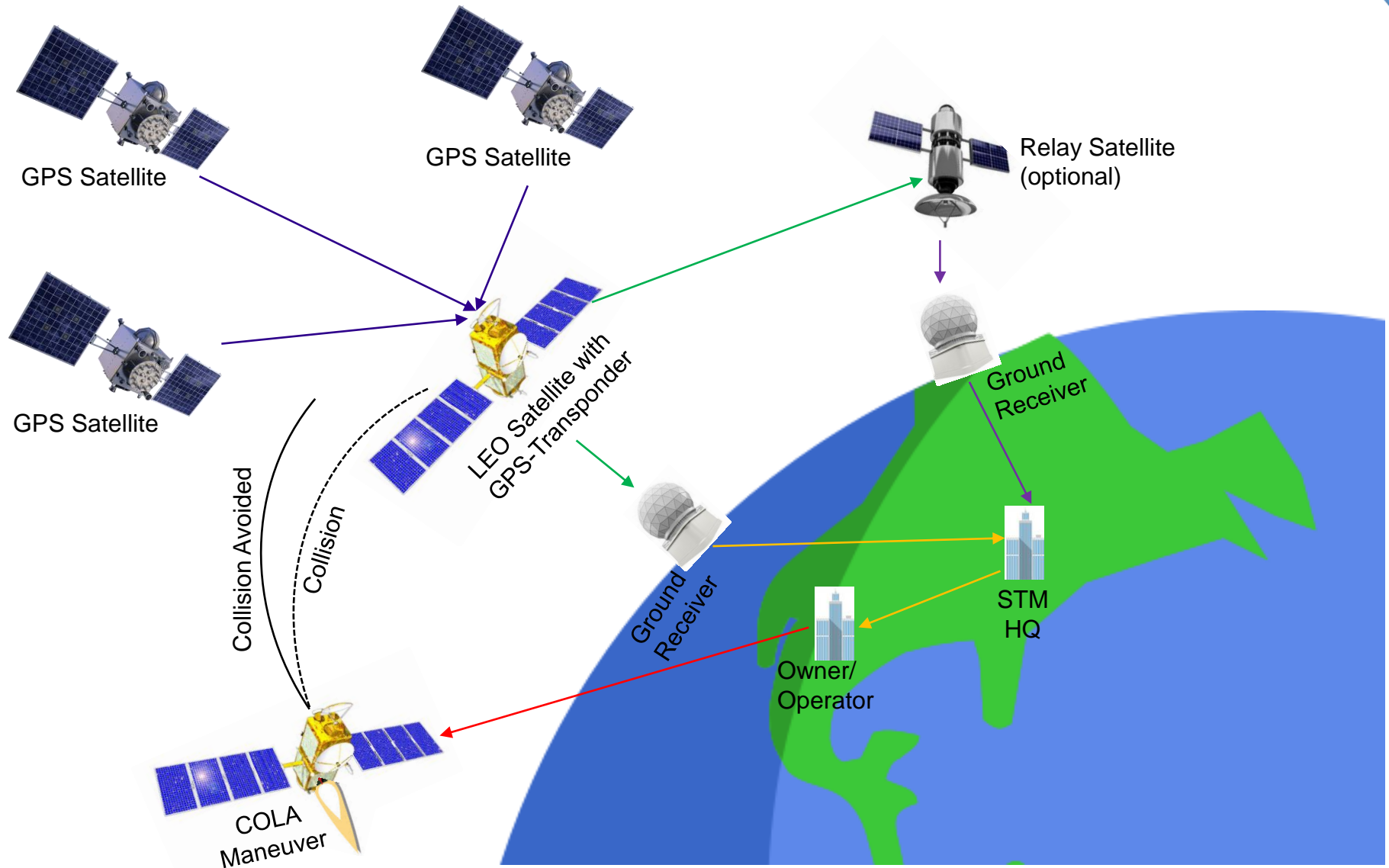
- A non-cooperative tracking network has a limited ability to track thrusting objects
 - *The network consists of “surveillance” (fence) assets as well as “tracking” assets*
 - *Track-and-predict system: not enough assets to maintain continuous custody of an object*
 - *Thrusting objects often lie outside of tracking box; they must be re-acquired and re-ID*
- There are many unknowns when attempting to model thrusting objects
 - *What is the intended & actual thrust-profile over time?*
 - *What direction is the thrust being applied in?*
 - Spacecraft attitude?
 - Configuration of solar panels?
 - Sets of thrusters & their on-times?
- Low-thrust objects are particularly difficult
 - *They are usually thrusting and not behaving according to modeled orbit perturbations*
 - *Thrust controls are often difficult to predict*
 - *This can be solved by transmitting frequent updates on position and optionally velocity, pointing, acceleration, etc.*





Background

OV-1: GPS-Transponder



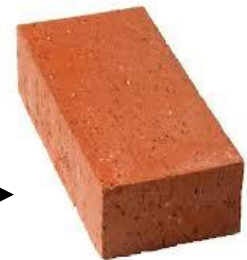


GPS Transponder Use Cases

Three Modes of Operation

- 1. Normal Mode:** This mode is active while the host spacecraft is controlled and providing power to the GPS Transponder. The transponder will transmit updates around once per minute
- 2. Thrust Mode:** This mode is activated by the host sending a trigger signal to the GPS Transponder (host will also provide power). The transponder will transmit updates around once per second. Acceleration and attitude data will be the most useful in this mode.
- 3. Debris Mode:** This mode is active while the host spacecraft is not providing power and is not controlling its attitude. Assume the host is a brick.

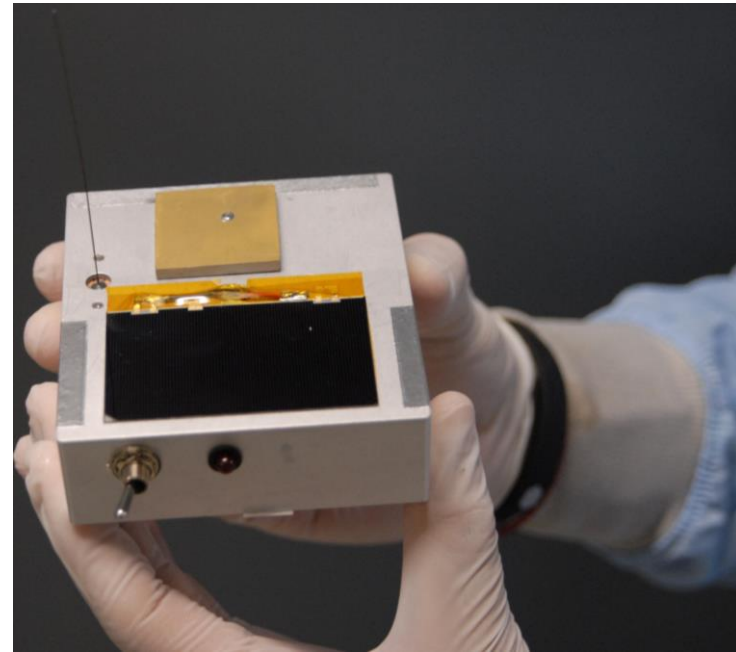
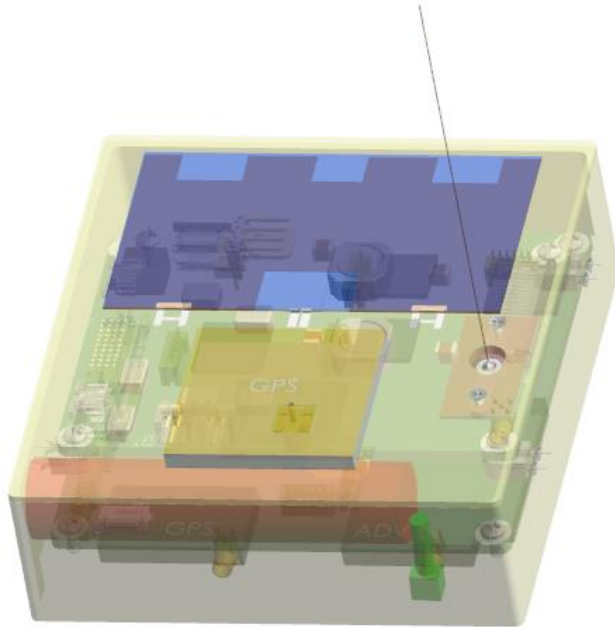
If a launch vehicle deploys a brick this system should operate without incident for years if not decades →





First Prototype

CAD Drawing and Photograph



- First Aerospace Corporation prototype
- 9.4 x 8.6 x 3.2 cm and 285 grams
- Final Prototype will be much smaller (deck of playing cards, 100 grams)



Questions?